

SIGNATURE \_\_\_\_\_ NAME \_\_\_\_\_

Student ID # \_\_\_\_\_

**Physics 410**

**Spring 2013**

**Prof. Anlage**

**Second Mid-Term Exam**

**5 April, 2013**

**CLOSED BOOK, Calculator Permitted, CLOSED NOTES**

**Point totals are given for each part of the question.**

If you run out of room, continue writing on the back of the same page. If you do so,  
make a note on the front part of the page!

Note: You must solve the problem following the instructions given in the problem.  
Correct answers alone will not receive full credit.

**Partial Credit:**

- Show Your Work! Answers written with no explanation will not receive full credit.
  - You can receive credit for describing the method you would use to solve a problem, even if you missed an earlier part.
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Problem	Credit	Max. Credit
1		25
2		25
3		20
4		30
<b>TOTAL</b>		<b>100</b>

$$\begin{aligned}
\vec{r} \cdot \vec{s} &= rs \cos \theta & \vec{r} \times \vec{s} &= \det \begin{bmatrix} \hat{x} & \hat{y} & \hat{z} \\ r_x & r_y & r_z \\ s_x & s_y & s_z \end{bmatrix} & \vec{F} &= m \ddot{\vec{r}} \quad \text{Constant } a: x(t) = x_0 + v_0 t + \frac{1}{2} a t^2; v(t) = v_0 + at; v_f^2 - v_i^2 = 2a\Delta x & \vec{f} &= -f(v) \hat{v} & f(v) &= bv + cv^2 \\
\vec{F} &= q(\vec{E} + \vec{v} \times \vec{B}) & m\dot{v} &= -\dot{m}v_{ex} + F^{ext} & v - v_0 &= v_{ex} \ln \frac{m_0}{m} & \vec{R} &= \frac{1}{M} \sum_{\alpha=1}^N m_\alpha \vec{r}_\alpha \\
\vec{\ell} &= \vec{r} \times \vec{p} & \vec{L} &= \sum_{\alpha=1}^N \vec{r}_\alpha \times \vec{p}_\alpha & \dot{\vec{L}} &= \vec{\Gamma}^{ext} & \Delta T &= T_2 - T_1 = \int_1^2 \vec{F} \cdot d\vec{r} = W(1 \rightarrow 2) \\
T &= mv^2/2 & U(\vec{r}) &= -W(\vec{r}_0 \rightarrow \vec{r}) = -\int_{\vec{r}_0}^{\vec{r}} \vec{F}(\vec{r}') \cdot d\vec{r}' & \vec{\nabla} \times \vec{F} &= 0 & \vec{F} &= -\vec{\nabla}U & E &= T + U_1 + \dots + U_n & \Delta E &= W_{nc} & t &= \sqrt{\frac{m}{2}} \int_{x_0}^x \frac{dx'}{\sqrt{E-U(x')}} & \vec{F}(\vec{r}) &= f(\vec{r}) \hat{r} & U &= U^{int} + U^{ext} = \sum_{\alpha} \sum_{\beta>\alpha} U_{\alpha\beta} + \sum_{\alpha} U_{\alpha}^{ext} & \text{Net force on particle } \alpha &= -\nabla_{\alpha} U & T + U &= \text{constant} \\
F &= -kx \leftrightarrow U = \frac{1}{2} kx^2 & \ddot{x} &= -\omega^2 x \leftrightarrow x(t) = A \cos(\omega t - \delta) & \ddot{x} + 2\beta \dot{x} + \omega_0^2 x &= 0 \leftrightarrow x(t) = Ae^{-\beta t} \cos(\omega_1 t - \delta) & (\text{assuming } \beta < \omega_0), \beta = \frac{2b}{m}, \text{damping force} &= -bv, \omega_0 = \sqrt{\frac{k}{m}}, \omega_1 &= \sqrt{\omega_0^2 - \beta^2} & F(t) &= mf_0 \cos(\omega t), x(t) &= A \cos(\omega t - \delta), \text{where } A^2 = \frac{f_0^2}{(\omega_0^2 - \omega^2)^2 + 4\beta^2 \omega^2} \\
S &= \int_{x_1}^{x_2} f[y(x), y'(x), x] dx, & \frac{\partial f}{\partial y} - \frac{d}{dx} \frac{\partial f}{\partial y'} &= 0 \\
S &= \int_{u_1}^{u_2} f[x(u), y(u), x'(u), y'(u), u] du, & \frac{\partial f}{\partial x} &= \frac{d}{du} \frac{\partial f}{\partial x'}, \text{ and } \frac{\partial f}{\partial y} &= \frac{d}{du} \frac{\partial f}{\partial y'} & \mathcal{L} &= T - U \\
\frac{\partial \mathcal{L}}{\partial q_i} &= \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{q}_i} \quad [i = 1, \dots, n] & p_i &= \frac{\partial \mathcal{L}}{\partial \dot{q}_i} & \mathcal{H} &= \sum_{i=1}^n p_i \dot{q}_i - \mathcal{L} & \vec{r} &= \vec{r}_1 - \vec{r}_2 & \mu &= \frac{m_1 m_2}{m_1 + m_2} \\
U_{eff} &= U(r) + U_{cf}(r) = U(r) + \frac{\ell^2}{2\mu r^2} & r(\varphi) &= \frac{c}{1+\epsilon \cos \varphi} \text{ for } F = -\frac{\gamma}{r^2}, \text{with } c = \frac{\ell^2}{\gamma \mu} \\
E &= \frac{\gamma^2 \mu}{2\ell^2} (\epsilon^2 - 1) \\
\vec{F}_{inertial} &= -m \vec{A} & \vec{\omega} &= \omega \hat{u} & \vec{v} &= \vec{\omega} \times \vec{r} & \left( \frac{d\vec{Q}}{dt} \right)_{S_0} &= \left( \frac{d\vec{Q}}{dt} \right)_S + \vec{\Omega} \times \vec{Q} \\
m \ddot{\vec{r}} &= \vec{F} + \vec{F}_{cor} + \vec{F}_{cf}, \text{with } \vec{F}_{cor} = 2m \vec{r} \times \vec{\Omega}, \text{and } \vec{F}_{cf} = m(\vec{\Omega} \times \vec{r}) \times \vec{\Omega} & \vec{g} &= \vec{g}_0 + (\vec{\Omega} \times \vec{R}) \times \vec{\Omega}
\end{aligned}$$